

Capstone Presentation

Project: Adversarial Learning - Medical Tomography

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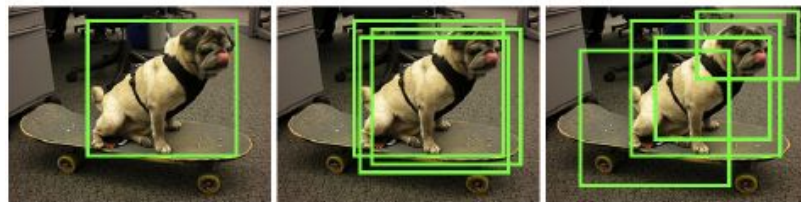
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Outline

1. ADA(Adversarial data augmentation): A Game-Theoretic Perspective on Data Augmentation for Object Detection
2. Detection of diabetic retinopathy(DR).
3. Difficulties and next steps

ADA(Adversarial data augmentation): A Game-Theoretic Perspective on Data Augmentation for Object Detection

- Introduce an adversarial function to generate (some distribution of) **maximally perturbed** version of the groundtruth which is hardest for the predictor to learn.
 - Why data augmentation: ground-truth wrong/not accurate....
 - How to add data augmentation: random translation, flipping, scaling...(manually add perturbations)
 - Problems: can be error-prone
- Adversary is not free but with **constraints** [e.g. $\text{features}(\text{new bb}) \approx \text{features}(\text{ori bb})$].
- First work to provide theoretic basis for data augmentation in terms of **an adversarial two player zero-sum game**.
 - predictor(maximize performance) vs constrained adversary(minimize expected performance).



Single Ground Truth

Random Augmentation

Adversarial Augmentation

Game Formulation

The **value/payoff** of the game for \mathbf{x} (the expected loss)

$$\mathbb{E}_{\substack{y'| \mathbf{a} \sim f \\ y| \mathbf{a} \sim P}} [\ell(y', y)] = \sum_{y', y} f(y'|x) \ell(y', y) P(y|x) \\ = \mathbf{f}^\top \mathbf{G} \mathbf{p}.$$

f: the vector of probabilities obtained from the predictor over all labels

G: the game matrix where each element contains the loss between two labels

p: the augmentor distribution vector

Definition

Primal Adversarial Data Augmentation(ADA-P):

$$\min_f \max_P \mathbb{E}_{\substack{\mathbf{a} \sim \mathcal{D}, \\ y'| \mathbf{a} \sim f, \\ y| \mathbf{a} \sim P}} [\ell(y', y)] \text{ such that:}$$

$$\mathbb{E}_{\substack{\mathbf{a} \sim \mathcal{D}, \\ y| \mathbf{a} \sim P}} [\phi(y, \mathbf{x})] = \mathbb{E}_{y, \mathbf{x} \sim \mathcal{D}} [\phi(y, \mathbf{x})] \quad \text{where}$$

$$\mathbb{E}_{y, \mathbf{x} \sim \mathcal{D}} [\phi(y, \mathbf{x})] = \frac{1}{N} \sum_{n=1}^N \phi(y_n, \mathbf{x}_n),$$

The Dual Adversarial Data Augmentation(ADA-D):

$$\min_{\theta} \mathbb{E}_{\mathbf{x}, y^* \sim \mathcal{D}} \left[\min_f \max_P \mathbb{E}_{\substack{y' \sim f, \\ y \sim P}} [\ell(y', y)] + \theta^\top \{ \phi(y, \mathbf{x}) - \phi(y^*, \mathbf{x}) \} \right].$$

Constraint Generation for Large Games

To solve the Games:

Nash Equilibrium \rightarrow Linear Programming

To solve ADA-D without explicitly constructing the entire payoff matrix G .

Key idea: To use a set of the **most violated constraints** to grow a game matrix that supports the equilibrium distribution, but is much smaller than the full game matrix.

\rightarrow Double Oracle Algorithm

Algorithm and Implementation of ADA

(One iteration)

Algorithm 1 ADA Equilibrium Computation

Input: Image x ; Parameters θ ; Ground Truth y^*

Output: Nash equilibrium, (f, p)

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1:  $\mathcal{Y} \leftarrow \text{EdgeBox}(x)$ 
2:  $\Phi = \text{CNN}(\mathcal{Y}, x)$ 
3:  $\psi \leftarrow \theta^\top (\Phi - \Phi(y^*))$ 
4:  $\mathcal{S}_p \leftarrow \mathcal{S}_f \leftarrow \arg\max_y \psi(y)$ 
5: repeat
6:    $(f, p, v_p) \leftarrow \text{solveGame}(\psi(\mathcal{S}_p), \text{loss}(\mathcal{S}_f, \mathcal{S}_p))$ 
7:    $(y_{\text{new}}, v_{\text{max}}) \leftarrow \max_y \mathbb{E}_{y' \sim f} [\text{loss}(y, y') + \psi(y)]$ 
8:   if  $(v_p \neq v_{\text{max}})$  then
9:      $\mathcal{S}_p \leftarrow \mathcal{S}_p \cup y_{\text{new}}$ 
10:  end if
11:   $(f, p, v_f) \leftarrow \text{solveGame}(\psi(\mathcal{S}_p), \text{loss}(\mathcal{S}_f, \mathcal{S}_p))$ 
12:   $(y'_{\text{new}}, v_{\text{min}}) \leftarrow \min_{y'} \mathbb{E}_{y \sim p} [\text{loss}(y, y')]$ 
13:  if  $(v_f \neq v_{\text{min}})$  then
14:     $\mathcal{S}_f \leftarrow \mathcal{S}_f \cup y'_{\text{new}}$ 
15:  end if
16: until  $v_p = v_{\text{max}} = v_f = v_{\text{min}}$ 
17: return  $(f, p)$ 

```

Preprocess steps to
extract features

Solve Nash equilibrium using linear programming
[Gurobi library](#)

$$\min_{\theta} \mathbb{E}_{\mathbf{x}, y^* \sim \mathcal{D}} \left[\min_f \max_P \mathbb{E}_{\substack{y' \sim f \\ y \sim P}} [\ell(y', y) + \theta^\top \{\phi(y, \mathbf{x}) - \phi(y^*, \mathbf{x})\}] \right].$$

Update θ :

$\nabla \theta$: from (f, p)

Preprocess Steps

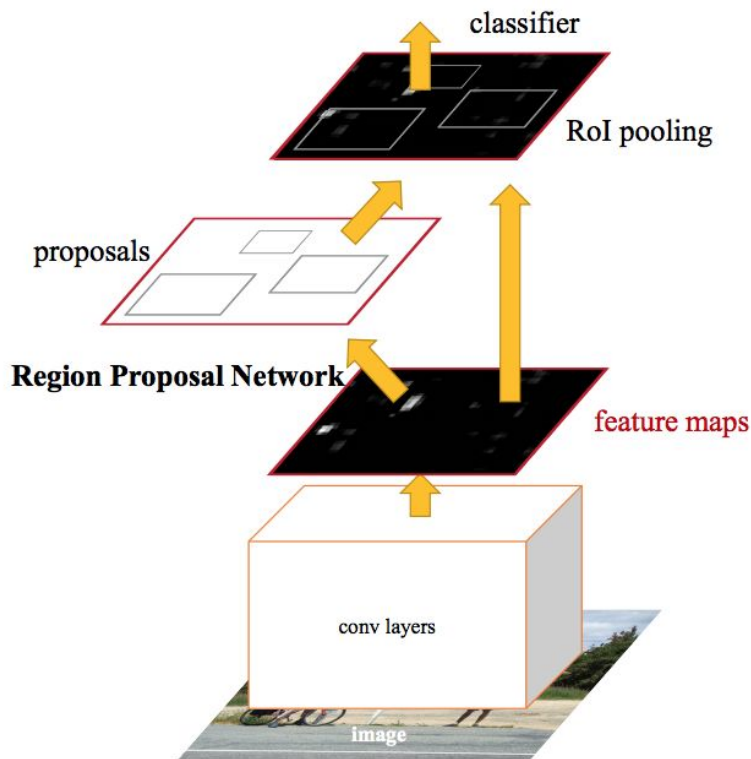
EdgeBox:

https://github.com/dculibrk/edge_boxes_with_python

CNN features:

https://github.com/longcw/faster_rcnn_pytorch

roi_pooling(vgg5_3 features, bounding boxes) \Rightarrow fc6 \Rightarrow fc7



Part Results of VOC2007 dataset

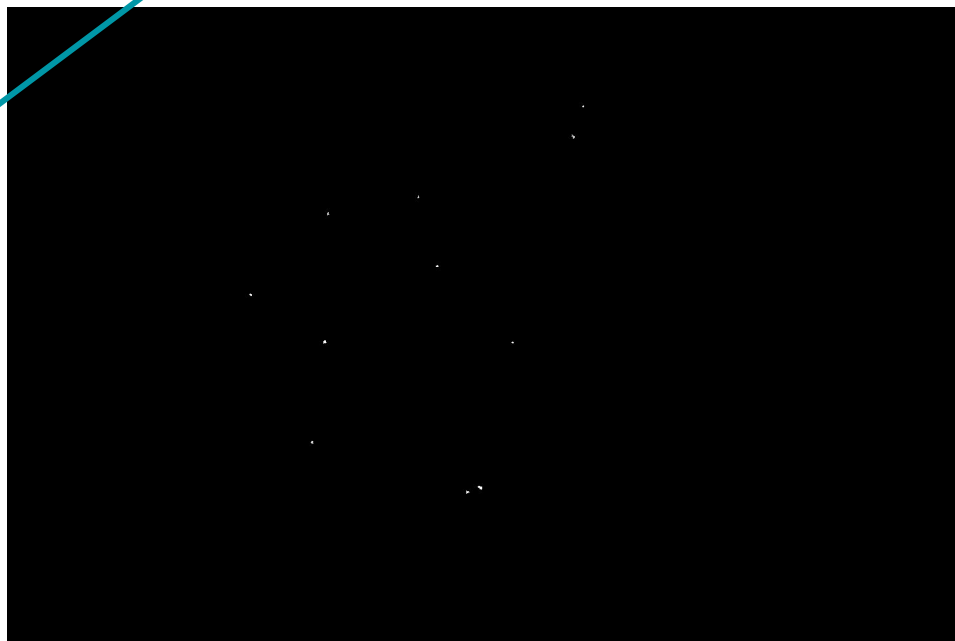
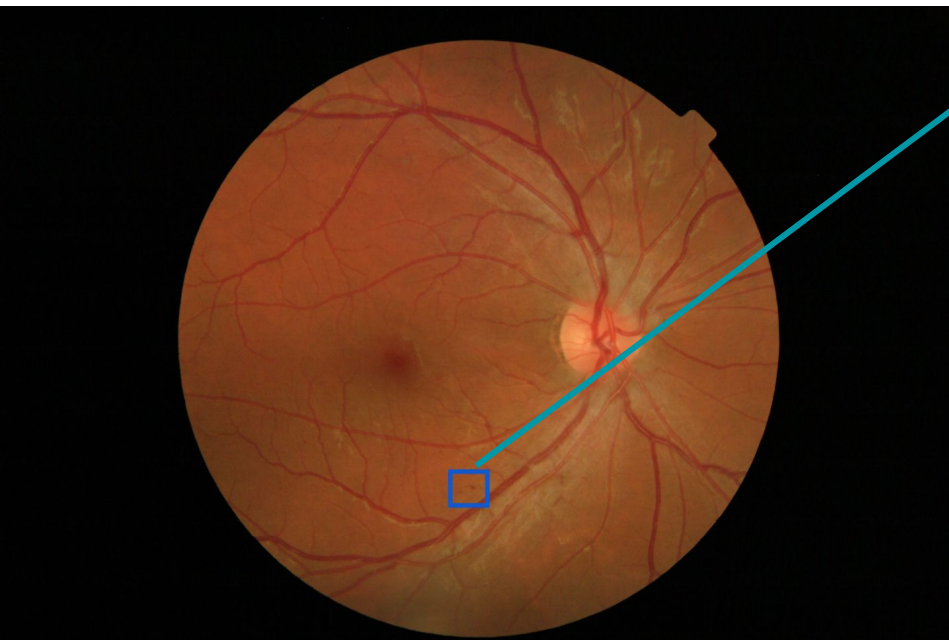
| IOU | aero | bike | bird | boat | bott | bus | car | cat | chair | cow | dint | dog | horse | mbike | perso n | plant | sheep | sofa | traun | tv |
|-----|------|------|------|------|------|-------|-------|-----|-------|-----|------|-----|-------|-------|------------|-------|-------|------|-------|----|
| 0.5 | -- | -- | -- | -- | -- | 0.803 | 0.711 | -- | -- | -- | -- | -- | -- | 0.760 | 0.689 | -- | -- | -- | -- | -- |
| 0.7 | -- | -- | -- | -- | -- | 0.628 | 0.461 | -- | -- | -- | -- | -- | -- | 0.636 | 0.403 | -- | -- | -- | -- | -- |

Table 6. ADA Generalization Across Deep Architectures. VOC2007 mAP for IoU>0.5.

| Model | VOC 2007 Object Category | | | | | | | | | | | | | | | | | | | | mAP |
|---------------------|--------------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| | Aero | Bike | Bird | Boat | Bott | Bus | Car | Cat | Chair | Cow | DinT | Dog | Horse | mbike | person | Plant | Sheep | Sofa | Train | TV | |
| ADA+VGG16 | 68.5 | 71.5 | 67.8 | 63.3 | 48.6 | 76.5 | 78.8 | 80.9 | 50.9 | 78.5 | 64.5 | 79.6 | 71.8 | 73.2 | 66.4 | 30.2 | 70.6 | 72.6 | 80.8 | 62.8 | 67.9 |
| SSVM+VGG16 | 73.6 | 76.4 | 63.7 | 46.1 | 44.0 | 76.0 | 78.4 | 80.0 | 41.6 | 74.2 | 62.8 | 79.8 | 78.0 | 72.5 | 64.3 | 35.0 | 67.2 | 67.2 | 70.8 | 71.4 | 66.1 |
| SVM+VGG16 [7] | 73.4 | 77.0 | 63.4 | 45.4 | 44.6 | 75.1 | 78.1 | 79.8 | 40.5 | 73.7 | 62.2 | 79.4 | 78.1 | 73.1 | 64.2 | 35.6 | 66.8 | 67.2 | 70.4 | 71.1 | 66.0 |
| ADA+AlexNet fc7 | 62.4 | 70.0 | 63.6 | 63.0 | 44.8 | 72.2 | 75.5 | 79.5 | 44.6 | 81.6 | 64.0 | 81.5 | 70.2 | 68.5 | 71.4 | 69.5 | 65.0 | 71.2 | 81.4 | 59.8 | 68.0 |
| SSVM+AlexNet fc7 | 68.2 | 72.9 | 57.3 | 44.2 | 41.8 | 66.0 | 74.3 | 69.2 | 34.6 | 54.7 | 54.3 | 61.3 | 69.8 | 68.7 | 58.5 | 34.6 | 63.6 | 52.5 | 62.6 | 63.5 | 58.6 |
| SVM+AlexNet fc7 [7] | 68.1 | 72.8 | 56.8 | 43.0 | 36.8 | 66.3 | 74.2 | 67.6 | 34.4 | 63.5 | 54.5 | 61.2 | 69.1 | 68.6 | 58.7 | 33.4 | 62.9 | 51.1 | 62.5 | 64.8 | 58.5 |
| ADA+ResNet101 | 76.4 | 74.8 | 72.4 | 64.0 | 52.5 | 84.0 | 81.9 | 86.0 | 48.5 | 83.5 | 64.8 | 82.0 | 73.5 | 77.0 | 72.4 | 36.6 | 74.4 | 74.8 | 81.4 | 65.6 | 71.3 |
| SSVM+ResNet101 | 68.0 | 70.2 | 69.3 | 54.3 | 46.5 | 76.2 | 78.8 | 85.0 | 46.8 | 80.2 | 63.2 | 78.1 | 69.5 | 71.4 | 61.8 | 36.8 | 68.1 | 69.1 | 73.6 | 64.5 | 66.5 |

Detection of diabetic retinopathy(DR)

Apply ADA to eye images for detection of diabetic retinopathy(DR detection)



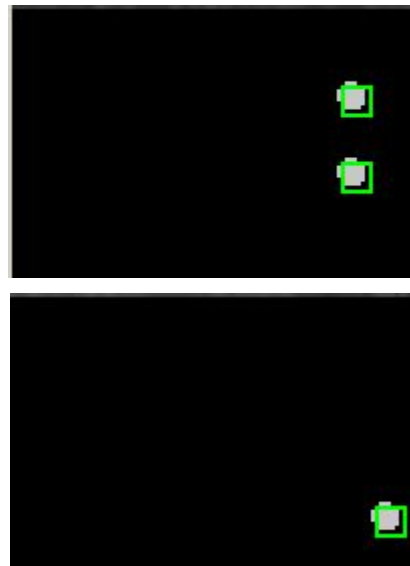
Detection of diabetic retinopathy(DR)

1. Dataset: e-optha-MA_(microaneurysm)

- a. 148 unhealthy images → 134 for training, 14 for test
- b. 233 healthy images → 199 for training, 24 for test

2. Generate baseline for detection(MA only)

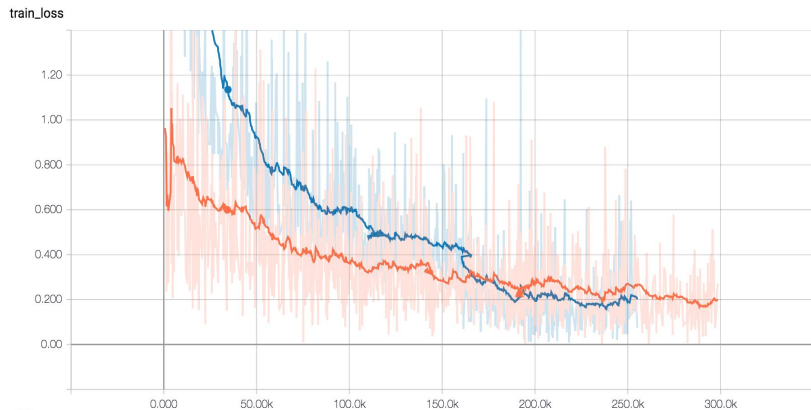
- a. Faster RCNN based methods
- b. Modifications
 - i. Generate bounding boxes: connect annotation lump and double the size of bounding boxes.
 - ii. Random crop 200 x 200 on the original images ~1000 x1000
 - iii. Enable faster rcnn to train on input images without any positive bounding boxes by only considering classification loss.
 - iv. Only Use small anchor sizes [2, 4, 8, 16] → [1, 2, 4]



Experiments

E1 training data: patches with positive bounding boxes(standard).

E2 training data: E1 data + without bounding boxes(my approach).

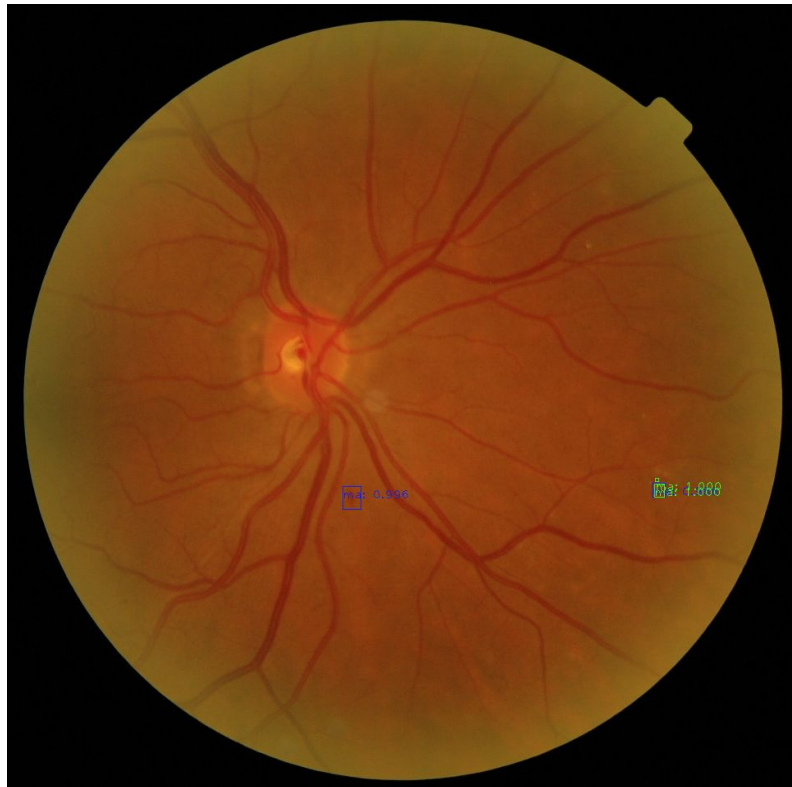


| <code>iou = 0.5</code> <code>bbox_thresh = 0.5</code> | bbox thresh | E1 (all positive) | E2 (half negative) |
|--|---------------|-------------------|--------------------|
| | avg_recall | 0.608 | 0.575 |
| | tot_recall | 0.556 | 0.481 |
| | avg_precision | 0.197 | 0.375 |
| | tot_precision | 0.169 | 0.382 |

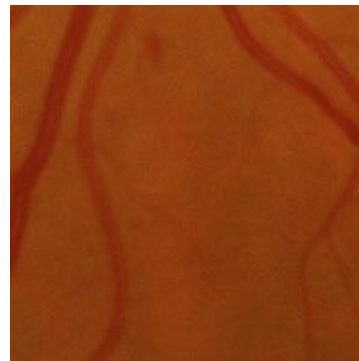
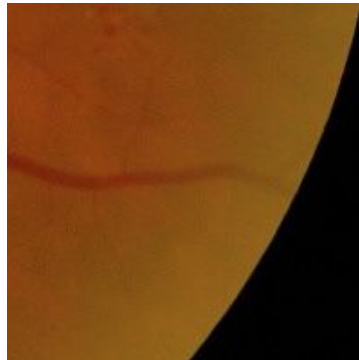
Comparison among different thresholds of E2

| | | | | | | | | | | | | |
|----|-----------|------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| E2 | iou = 0.5 | bbox thresh | 0. | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 |
| | | AUC(image level) | 0.5 | 0.860 | 0.860 | 0.878 | 0.878 | 0.878 | 0.881 | 0.887 | 0.881 | 0.892 |
| | | AP(image level) | 0.368 | 0.804 | 0.800 | 0.819 | 0.912 | 0.805 | 0.803 | 0.820 | 0.793 | 0.798 |
| | | avg_recall | 0.641 | 0.595 | 0.580 | 0.580 | 0.587 | 0.575 | 0.585 | 0.565 | 0.527 | 0.528 |
| | | tot_recall | 0.602 | 0.519 | 0.491 | 0.491 | 0.5 | 0.481 | 0.491 | 0.472 | 0.454 | 0.454 |
| | | avg_precision | 0.001 | 0.268 | 0.294 | 0.322 | 0.360 | 0.375 | 0.390 | 0.404 | 0.480 | 0.537 |
| | | tot_precision | 0.001 | 0.257 | 0.286 | 0.313 | 0.353 | 0.382 | 0.408 | 0.418 | 0.480 | 0.544 |

False Positives

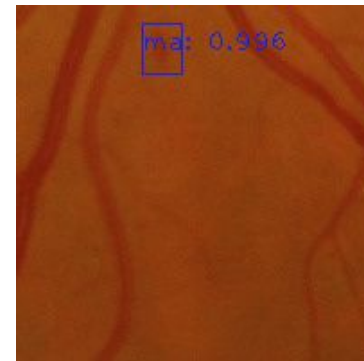
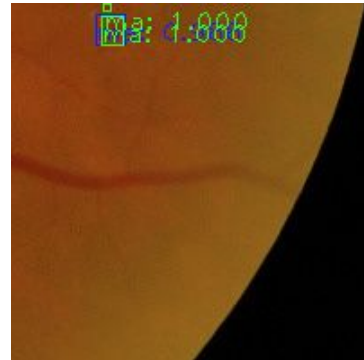


Original patches

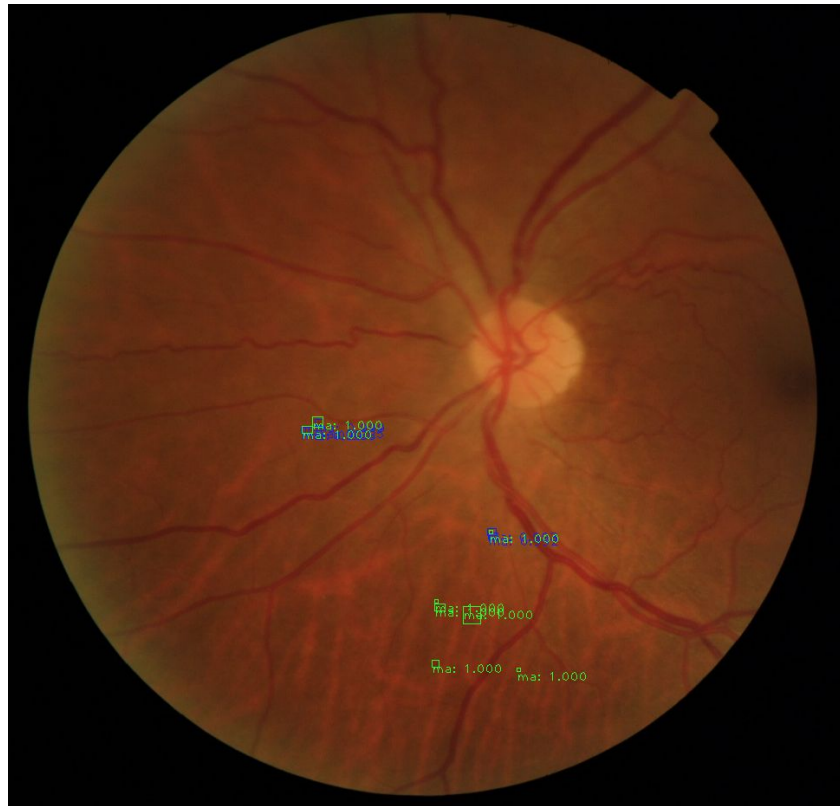


Groundtruth

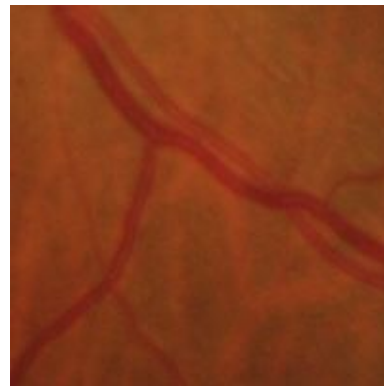
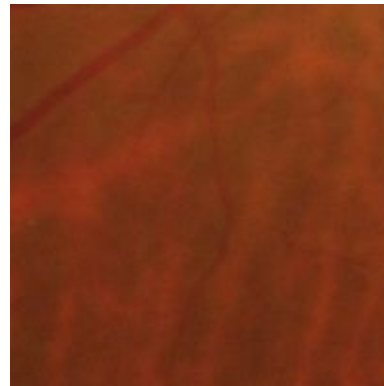
Predicted



False Negatives



Original patches



Groundtruth
Predicted



Next steps

- Pretrain VGG with image-level labeled DR dataset like Messidor
- Apply ADA to improve the detection performance, e.g. using maximally disturbed contrast or resolution as data augmentation.
- Apply Adversarial Robust Cuts for segmentation
 - a. [ARC: Adversarial Robust Cuts for Semi-Supervised and Multi-Label Classification](#)
 - b. Another adversarial learning algorithm, can be used for pixel classification
 - c. Compare with Mask RCNN

Q&A