

Embedded Multi-Person Pedestrian Tracking and Detection

MSCV19 Capstone Project, Internal(CMU)

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Introduction

- Problem
 - Detect and track multiple people
 - Deal with occlusion, large appearance changes
- Motivation
 - Real-time multi-person pedestrian tracking
 - Visual analysis, automatic driving, robotics
- Solution
 - Track by detection - SiameseRPN (Single Object)
 - Multiple object extension



Siamese RPN for Single Object Tracking

Siamese RPN

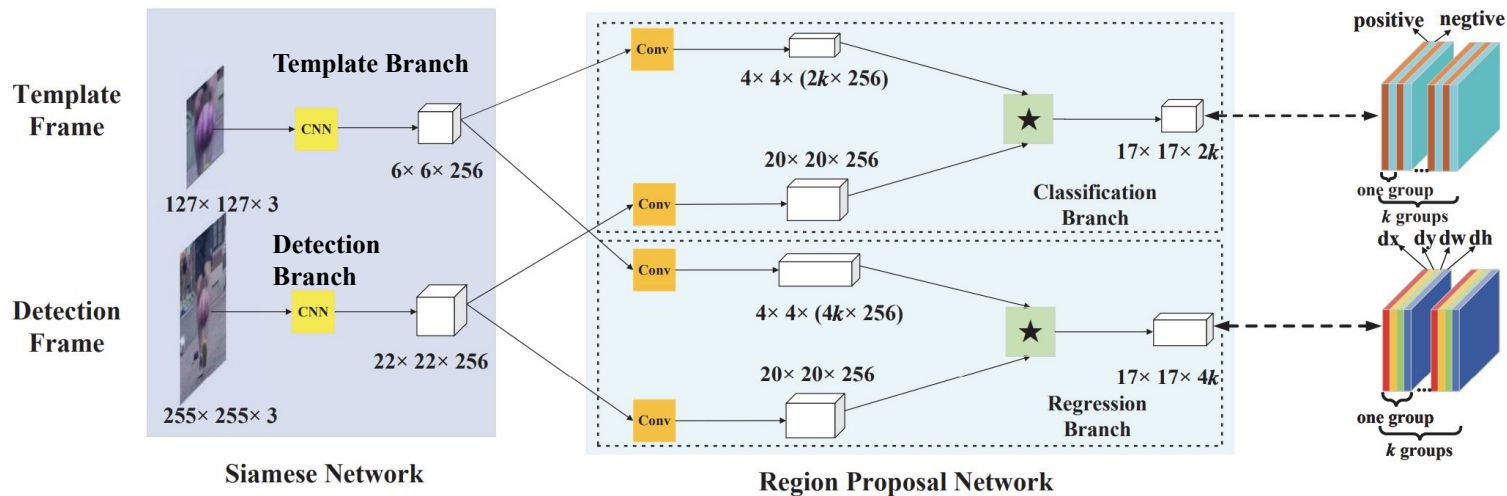
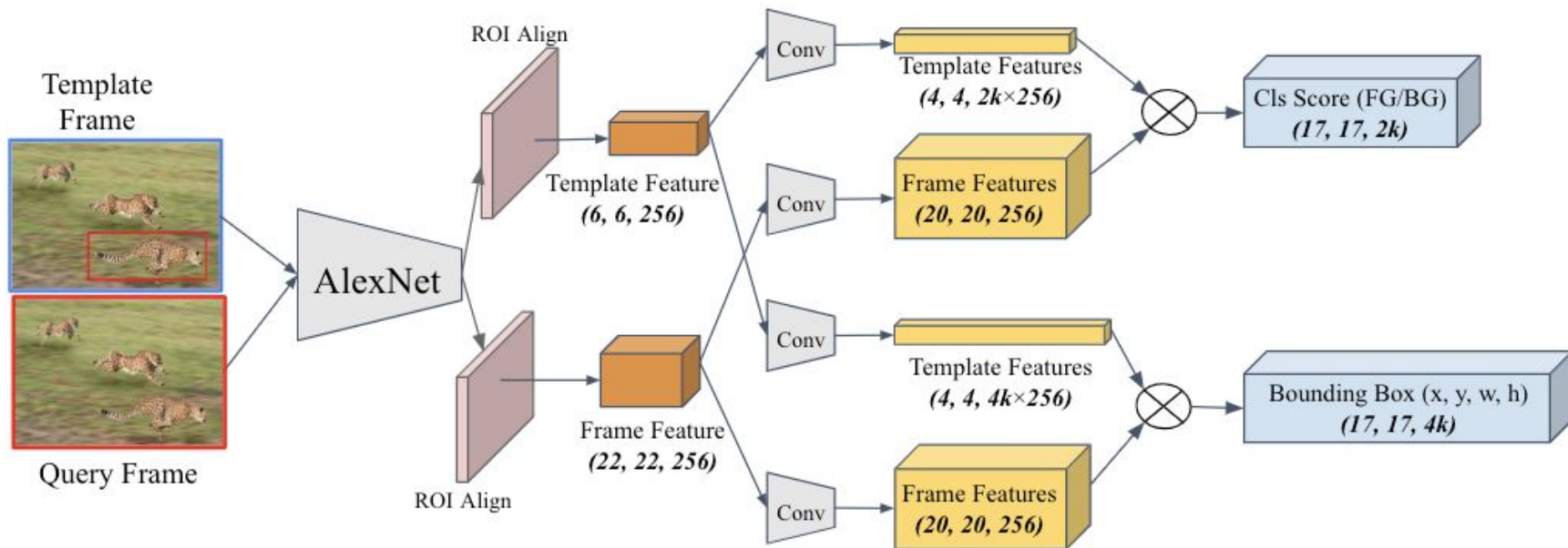


Figure 2: Main framework of Siamese-RPN: left side is Siamese subnetwork for feature extraction. Region proposal subnetwork lies in the middle, which has two branches, one for classification and the other for regression. Pair-wise correlation is adopted to obtain the output of two branches. Details of these two output feature maps are in the right side. In classification branch, the output feature map has $2k$ channels which corresponding to foreground and background of k anchors. In regression branch, the output feature map has $4k$ channels which corresponding to four coordinates used for proposal refinement of k anchors. In the figure, \star denotes correlation operator.

Siamese RPN

- Re-implementating Siamese RPN
 - Training & Testing have been implemented
 - note: this is migrated from an unofficial reimplementation of SiameseRPN
 - Testing results (finetune from pretrained weights on VOT dataset)
 - Training EAO (Expected Average Overlap): 0.5240
 - Testing EAO: 0.3085

Siamese RPN with RoI Align



Siamese RPN with RoI Align

- Siamese RPN with RoI Align
 - Training & Testing have been implemented
 - Results (finetune from pretrained weights on VOT dataset)
 - Training EAO: 0.6045
 - Testing EAO: 0.0785
- Will be used for MOT tracking to save computation

Some Visualizations



Red - SiamRPN (finetuned)
Blue - SiamRPN Rol (finetuned)



Black - Official DaSiameseRPN
Green - Ground Truth

What's next

- Training code for official SiameseRPN implementation
- Improving test performances
 - Investigate into low test performance using RoI
 - Use official SiameseRPN implementation
 - NMS with size penalty, distance penalty
- Consider how to merge with Multi-Object Tracking

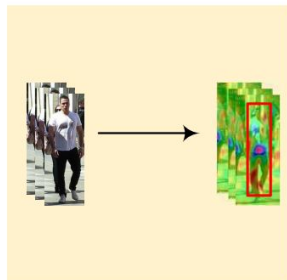
SiamRPN Extension for Multiple Object Tracking

Extend SiamRPN for Multi Object Tracking

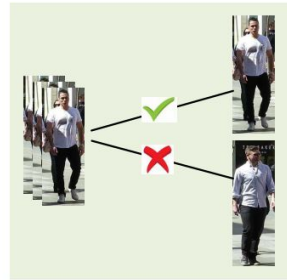
- Single Object Tracking
 - Given a template, do tracking
- Multiple Object Tracking
 - 1. Given several templates, do tracking
 - 2. Decide when to add new templates



Detection

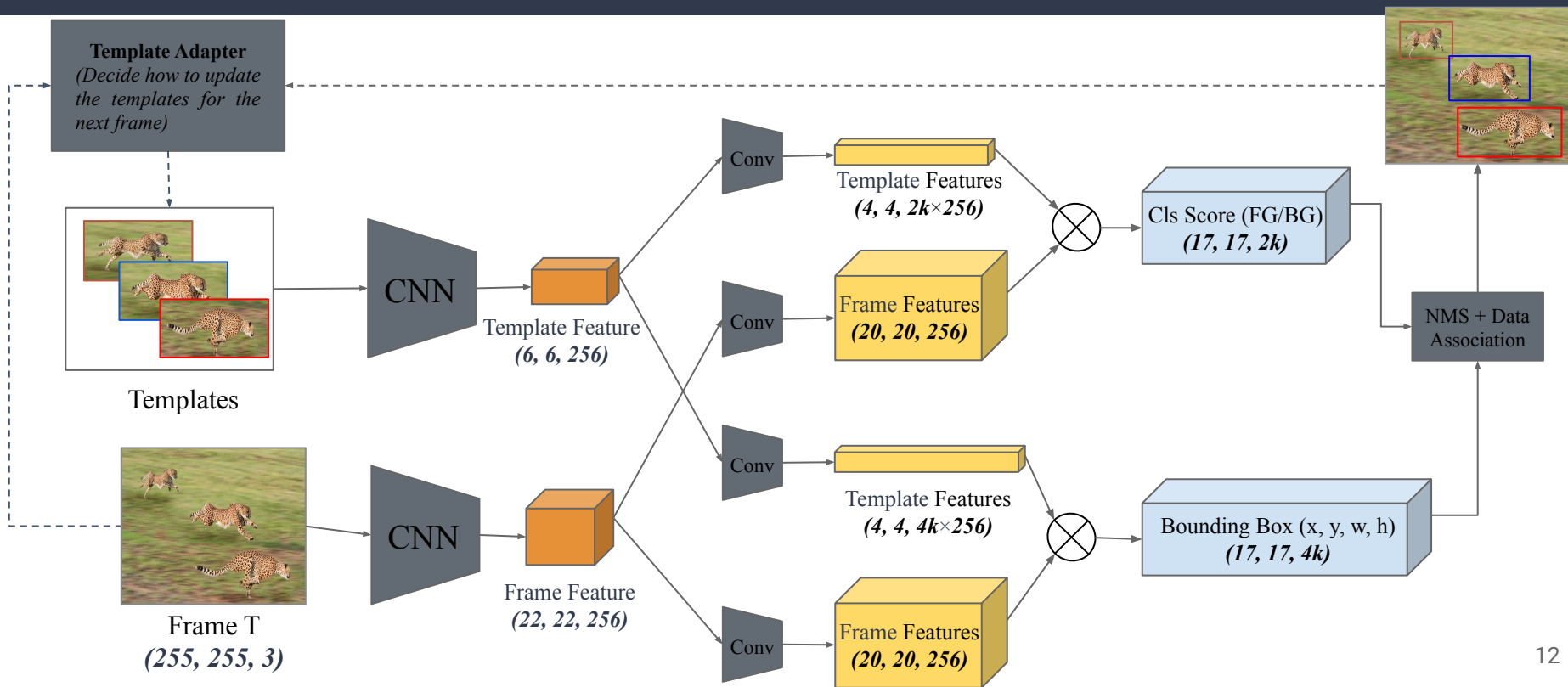


Single object tracking

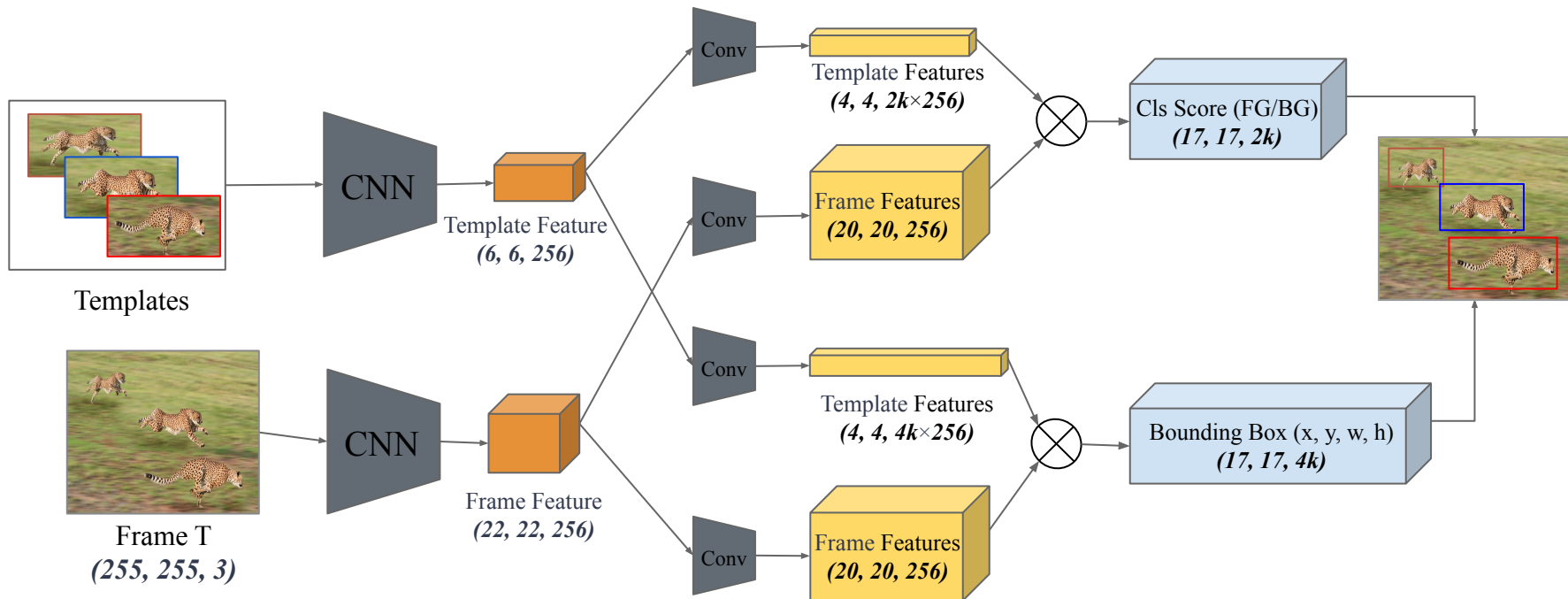


Data association

Extend SiamRPN for Multi Object Tracking



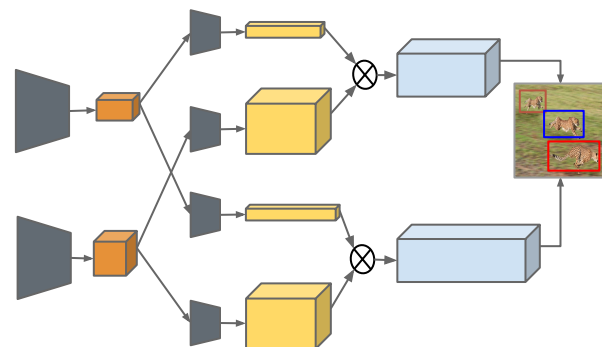
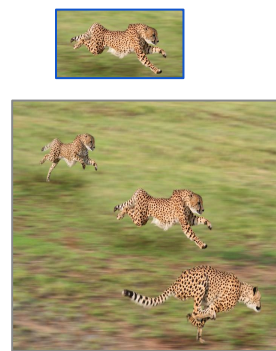
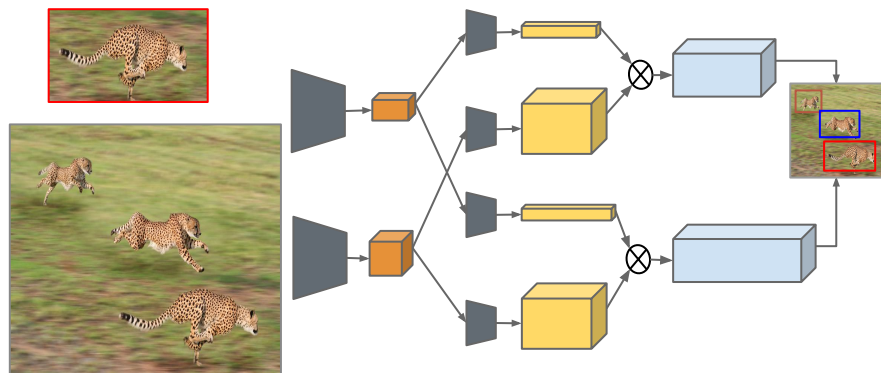
Extend SiamRPN for Multi Object Tracking



Ideas for Tracking

- Basic Idea: For loop
 - Initialize different single object tracker for each object
 - Time and memory complexity increase linearly
- All single object tracker share the same network weight
 - Pre-compute correlation filters and save
 - Fix the memory issue
- Introduce Communication between templates
 - Add Distractor-aware loss and fine-tune
- More Ideas
 - ROI Pooling

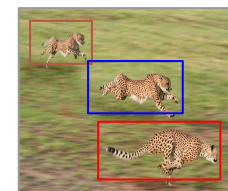
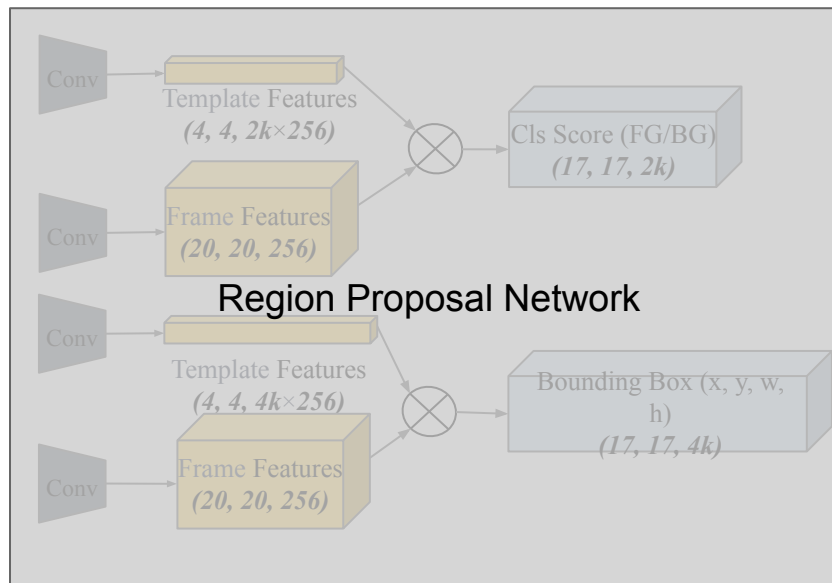
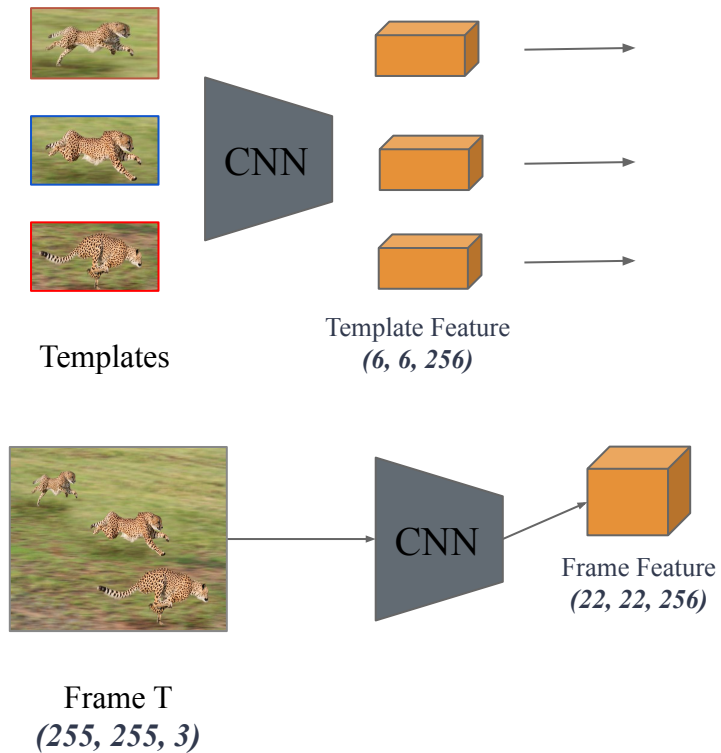
Pipeline 1: For loop



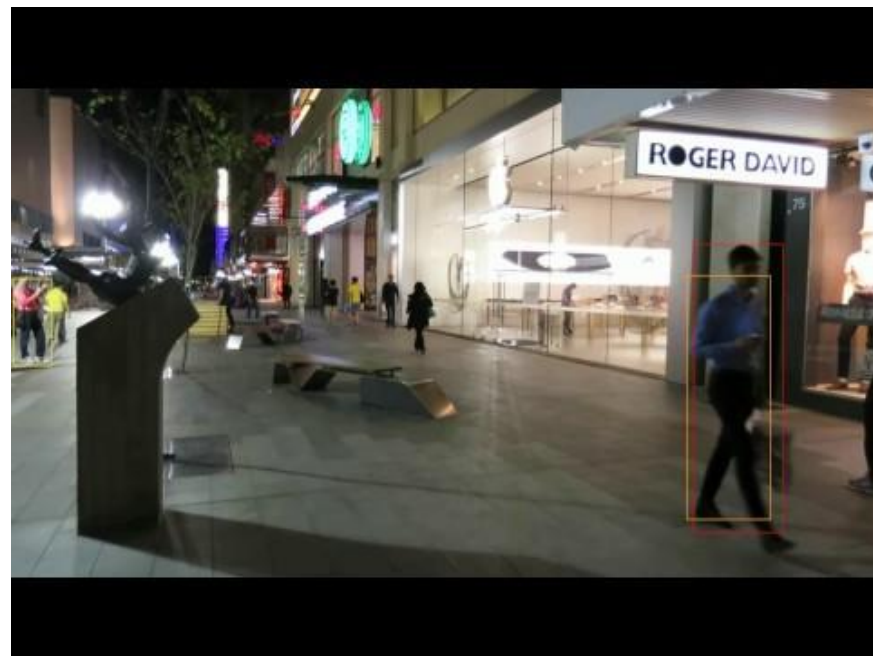
Ideas for Tracking

- Basic Idea: For loop (Done)
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Pipeline 2:

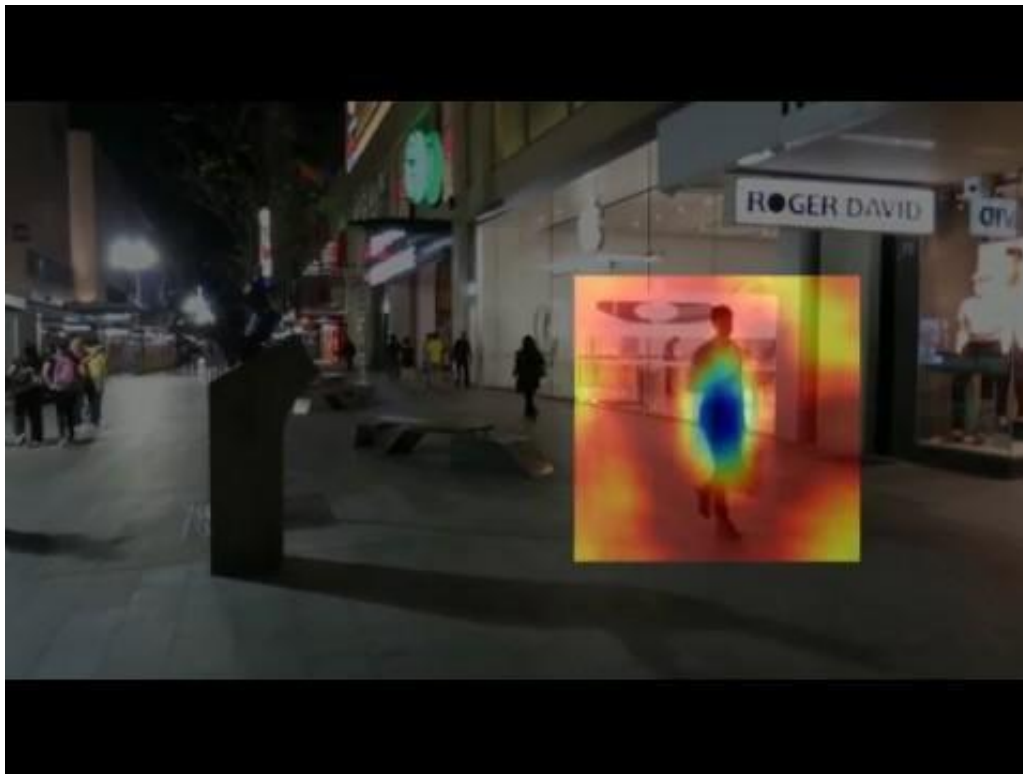


Visualization Results



Visualization Response

Template:



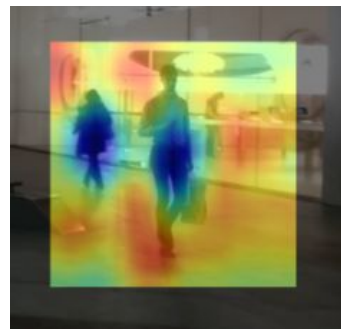
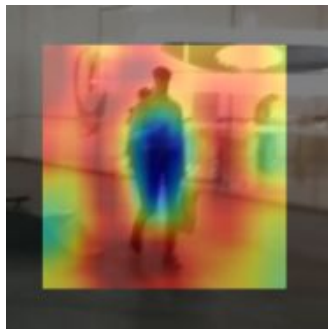
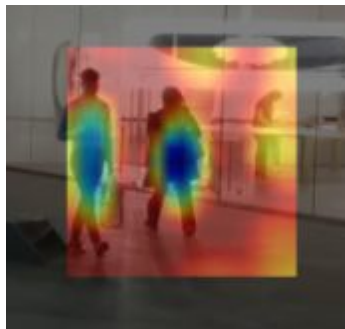
Visualization Response

Template:

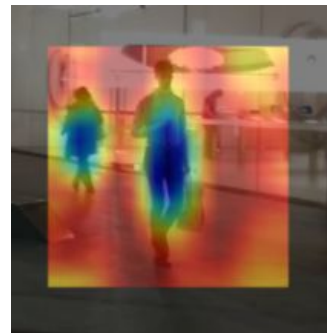
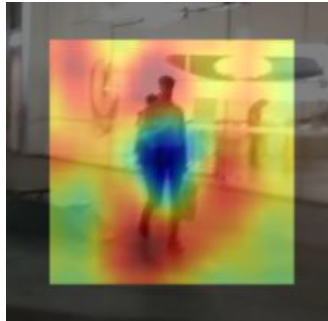
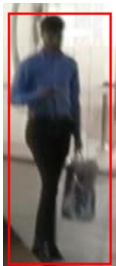


Visualization Response

Template:



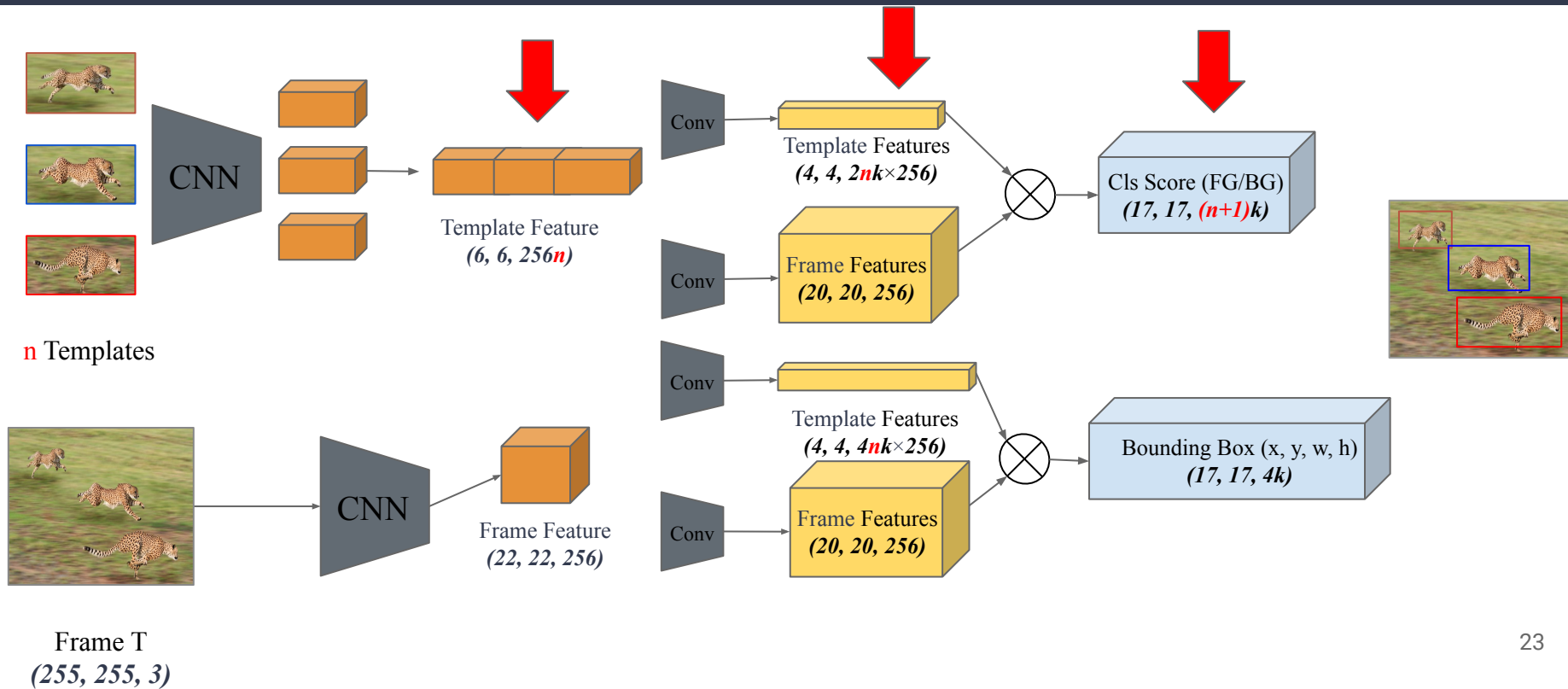
Template:



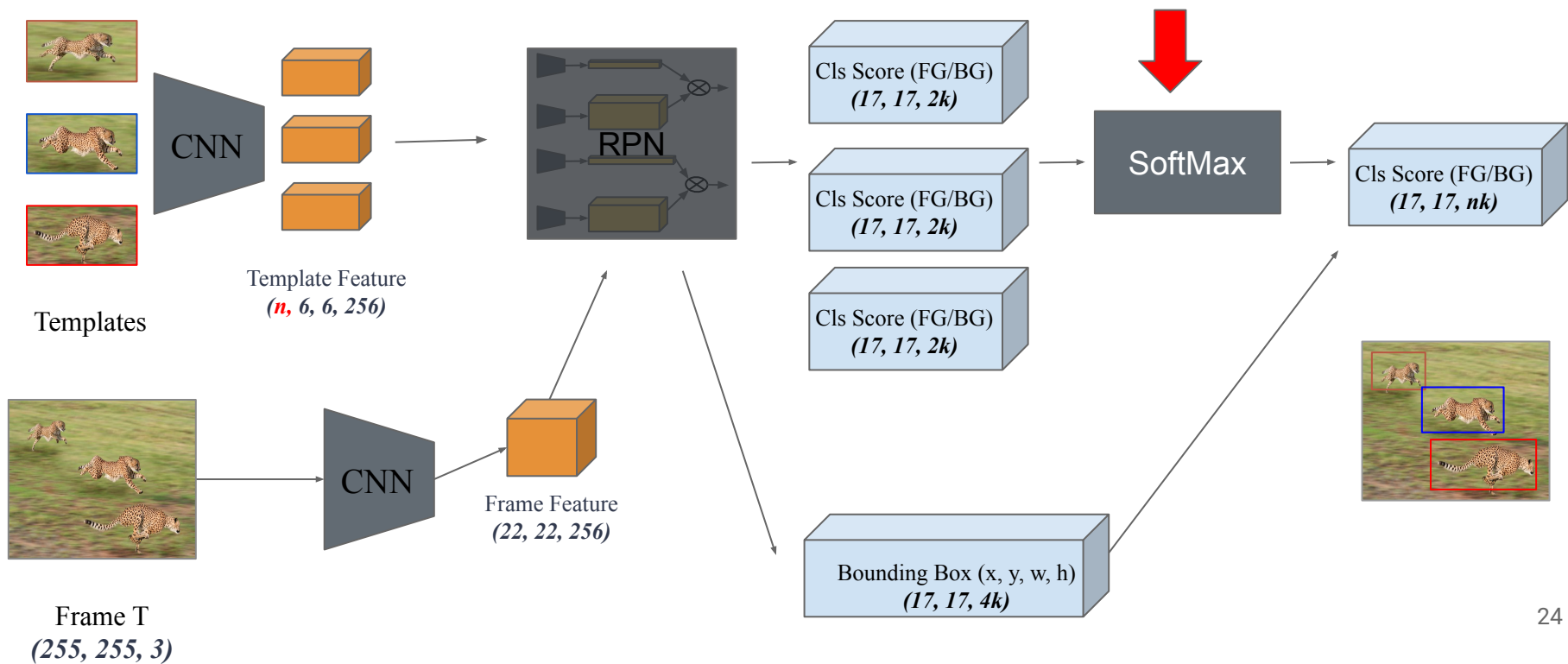
Ideas for Tracking

- Basic Idea: For loop (Done)
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 - Fix the memory issue
- Introduce Communication between templates
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- More Ideas
 - ROI Pooling

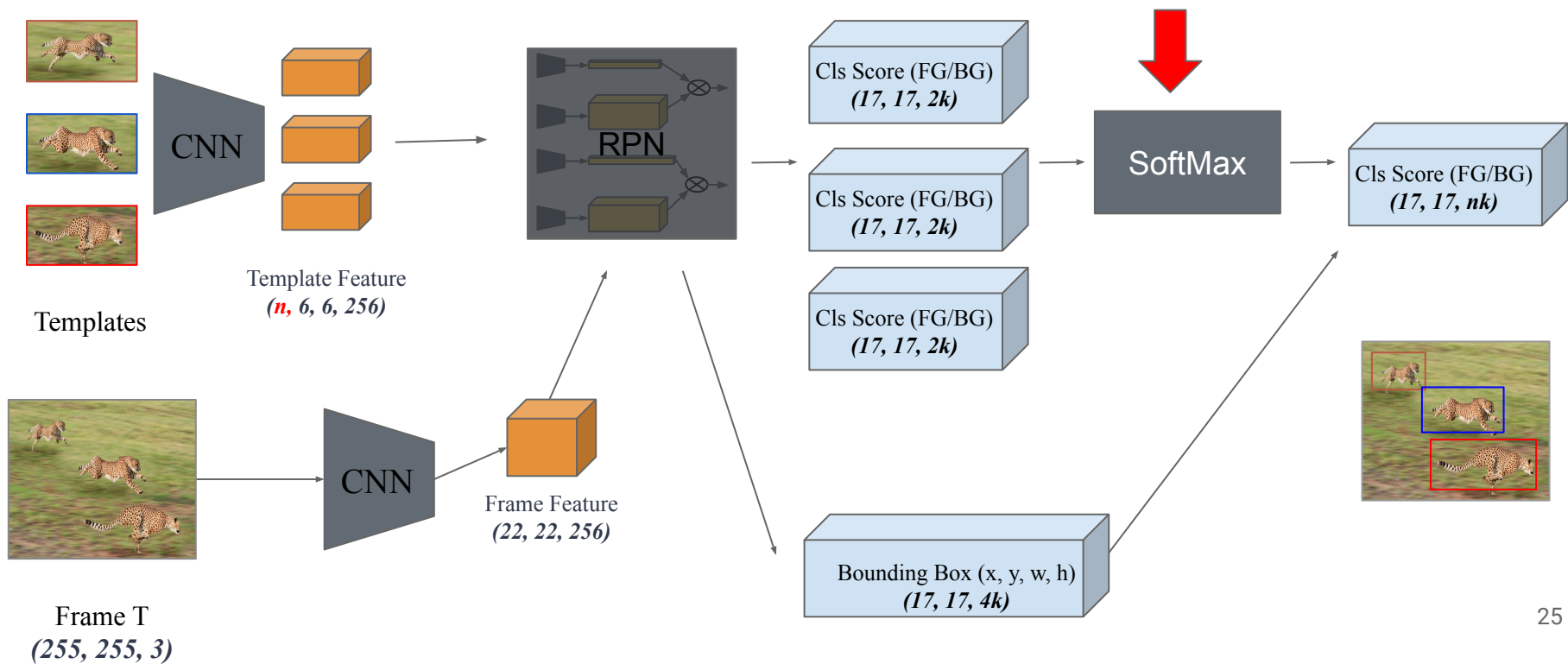
Pipeline 3: Connect all templates



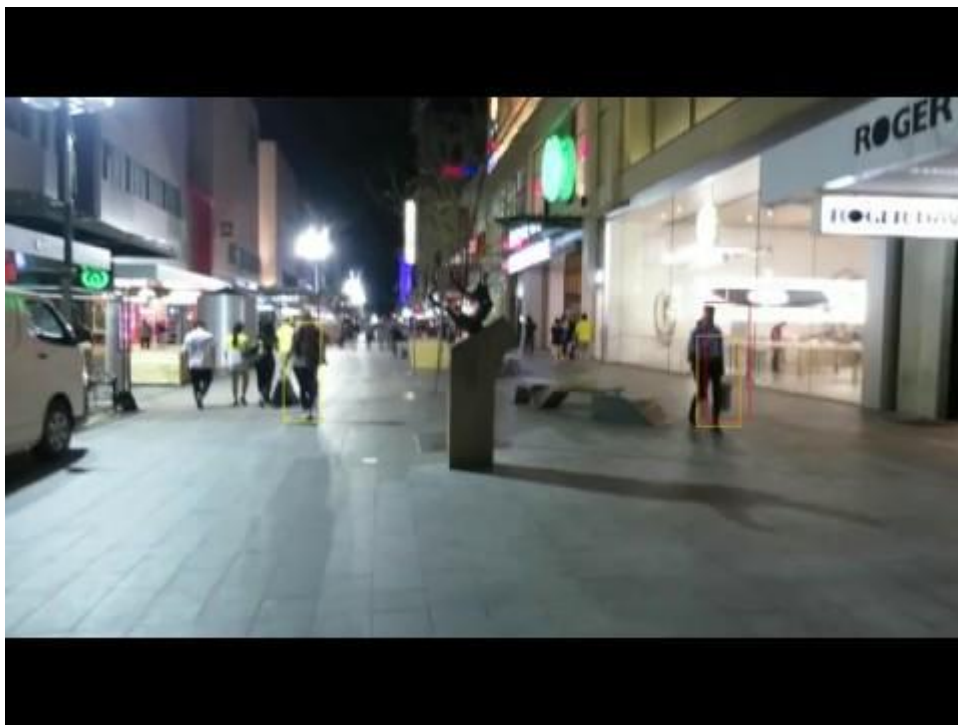
Pipeline 4: Connect all templates



Pipeline 4: Connect all templates



Visualization (not working, still in progress)



Ideas for Tracking

- Basic Idea: For loop (Done)
 - Initialize different single object tracker for each object
 - Time and memory complexity increase linearly
- All single object tracker share the same network weight (Done)
 - Pre-compute correlation filters and save
 - Fix the memory issue
- Introduce Communication between templates (In Progress)
 - Add Distractor-aware loss and fine-tune
- More Ideas
 - ROI Pooling to speed up

Timeline

Task	Person	Time	Result
SiamRPN test on VOT using official Code, Verify numbers	Richard		Done
Finetune SiamRPN on VOT, Verify numbers	Richard	4.11	In Progress
Finetune SiamRPN with ROI Pooling, Verify numbers	Richard	4.11	Code Done, need EXP
Two-template SlamRPN: A uniform architecture	Chunhui	4.11	In Progress
Two-template SlamRPN with ROI Pooling	Chunhui	4.18	
Data Association: concept design + implement		4.25	
Evaluation on MOT benchmark		5.3	